

## **Meeting Minutes – January 5, 2007**

Attendance: Natalia Vlajic, Nelson, Michael Portnoy, Patrick Tayao, Doug Stamp, and Hamdi Roumani

- Objective of the meeting was to discuss algorithms that will be implemented on the Robot and a relative timeline for implementation.
- Michael presented 3 different algorithms for techniques to bridge the gap. One of his algorithms were selected to be implemented based on the scale of the project
- Nelson presented geolocation techniques that can be implemented. This will allow determination of each static node's x and y coordinates on a given set.
- Since the WSN kit just arrived, we proposed a period of learning the kit and will be presenting to her and her graduates functionality of the kit and what features will be available for use.
- Three presentations will be done by the Widar group: WSN functionality, Bridging communication with known geolocation implementation and Bridging communication with unknown geolocation implementation. These presentations will commence at the end of each upcoming months( January, February and March).
- Weekly meetings will start to occur with Prof. Vlajic every Friday at 10 am to discuss project status.